



**COINCIDENCES AND FIXED POINTS OF HYBRID MAPS IN SYMMETRIC
SPACES**

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ABSTRACT. The purpose of this paper is to obtain a new coincidence theorem for a single-valued and two multivalued operators in symmetric spaces. We derive fixed point theorems and discuss some special cases and applications.

Key words and phrases: Coincidence, Fixed point, Hybrid maps, Symmetric space.

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1. INTRODUCTION

$$\sup_{a \in A} \inf_{b \in B} \lim_{c \in C}$$

Fixed point theorems for multivalued contractions were first initiated by Markin [16] and Nadler, Jr. [18]. Subsequently, a number of generalizations of Nadler's multivalued contraction principle were obtained in different settings (see, for instance, [4, 12, 14, 17, 19], [22]–[26], [28, 30] and several references thereof). Fixed point theory in multivalued analysis finds applications in optimization/control theory, operating systems, disjunctive logic programs, information theory, fractals and other areas of mathematical sciences (see, for instance, [7, 11, 15, 28] and [30]). Hybrid fixed point theory for nonlinear single-valued and multivalued maps is a recent development in multivalued analysis (see, for instance, [3, 14, 19], [21]–[26] and references thereof). Recently Aamri et al. [1] and [2], Hicks and Rhoades [9, 10] and Moutawakil [17] have obtained some fixed point theorems for single-valued and multivalued maps in d -bounded symmetric spaces (see also [13]). The purpose of this paper is to present coincidence theorems for hybrid contractions on symmetric spaces (not necessarily d -bounded). The completeness requirement of the space is also relaxed. We derive fixed point theorems generalizing their results ([10] and [17]) and discuss some applications.

2. PRELIMINARIES

We will follow the notations and definitions used in [1, 2, 9, 10, 17] and [27].

Definition 2.1. A symmetric function on a nonempty set X is a nonnegative real-valued map d on $X \times X$ such that

- (i) $d(x, y) = 0$ if and only if $x = y$, and
- (ii) $d(x, y) = d(y, x)$ for all $x, y \in X$.

Let d be a symmetric on a set X and for $r > 0$ and any $x \in X$, let

$$B(x, r) = \{y \in X : d(x, y) < r\}.$$

A topology $t(d)$ on X is given by $U \in t(d)$ if and only if for each $x \in U$, $B(x, r) \subseteq U$, for some $r > 0$.

A symmetric d is a semi-metric if for each $r > 0$, $B(x, r)$ is a neighbourhood of x in the topology $t(d)$.

Definition 2.2. Let (X, d) be a symmetric space. Then:

A nonempty subset P of X is d -closed if and only if $\bar{P}_d = P$, where

$$\bar{P}_d = \{x \in X : d(x, P) = 0\}$$

and

$$d(x, P) = \inf \{d(x, p) : p \in P\}.$$

Definition 2.3. A nonempty set P is called d -bounded if and only if $\delta_d(P) < \infty$, where

$$\delta_d(P) = \sup \{d(x, p) : x, p \in P\}.$$

Definition 2.4. The space (X, d) is S -complete if for every d -Cauchy sequence $\{x_n\}$, there exists x in X with

$$\lim_{n \rightarrow \infty} d(x_n, x) = 0.$$

Definition 2.5. Let (X, d) be a symmetric space and let $CB(X)$ be the set of all nonempty d -closed and d -bounded subsets of X . The Hausdorff metric H induced by the symmetric d is defined in the usual way:

$$H(A, B) = \max \left\{ \sup_{b \in B} d(b, A), \sup_{a \in A} d(a, B) \right\}$$

for all $A, B \in CB(X)$. As noted in [1] and [17], the hyper space $(CB(X), H)$ is a symmetric space induced by the symmetric d .

Definition 2.6. The maps $f : X \rightarrow X$ and $T : X \rightarrow CB(X)$ are (IT)-commuting at a point $x \in X$ if $fTx \subset Tfx$ [12].

This definition essentially due to Itoh and Takahashi [12] has widely been used in hybrid fixed point theory (see, for instance, [24]–[27]).

We remark that (IT)-commutativity of a hybrid pair T and f at a coincidence point $x \in X$ is more general than its compatibility and weak compatibility at the same point (see [25, Example 1]).

In our results we need the following axioms essentially due to Wilson [29] for the symmetric spaces (see also [1, 10] and [17]). Let (X, d) be a symmetric space. Then

(W.3) Given $\{x_n\}$, x and y in X ,

$$\lim_{n \rightarrow \infty} d(x_n, x) = 0 \text{ and } \lim_{n \rightarrow \infty} d(x_n, y) = 0 \text{ imply } x = y.$$

(W.4) Given $\{x_n\}$, $\{y_n\}$ and x in X ,

$$\lim_{n \rightarrow \infty} d(x_n, x) = 0 \text{ and } \lim_{n \rightarrow \infty} d(x_n, y_n) = 0 \text{ imply that } \lim_{n \rightarrow \infty} d(y_n, x) = 0.$$

If $t(d)$ is Hausdorff then (W.3) holds (see Hicks and Rhoades [10, p. 330]).

(iii) X is S-complete if for every d -Cauchy sequence $\{x_n\}$, there exists an x in X with

$$\lim_{n \rightarrow \infty} d(x_n, x) = 0.$$

(iv) X is d -Cauchy complete if for every d -Cauchy sequence $\{x_n\}$, there exists an x in X with $x_n \rightarrow x$ in the topology $t(d)$.

We remark that S-completeness implies d -Cauchy completeness (see [1] and [17]).

We shall need the following results:

Lemma 2.1. Let (X, d) be a symmetric space. Let M be a d -bounded subset of X and $\{y_n\}$ be a sequence in M such that

$$d(y_j, y_{j+1}) \leq qd(y_{j-1}, y_j), j = 1, 2, 3, \dots, \text{ where } 0 \leq q < 1.$$

Then $\{y_n\}$ is a d -Cauchy sequence.

Proof. It may be completed using the relevant part of the proof of Theorem 2.2.1 [17, p. 28]. ■

Lemma 2.2. ([17]) Let (X, d) be a symmetric space. Let $A, B \in CB(X)$ and $\lambda > 1$. For each $a \in A$, there exists $b \in B$ such that

$$d(a, b) \leq \lambda H(A, B).$$

Indeed, this result in a metric space is essentially due to Nadler, Jr. [18] and Ćirić [4].

3. MAIN RESULTS

First we give a coincidence theorem.

Theorem 3.1. *Let (X, d) be a symmetric space satisfying (W.4). Let $f : X \rightarrow X$ and $S, T : X \rightarrow CB(X)$ such that*

$$(3.1) \quad S(X) \cup T(X) \subseteq f(X),$$

$$(3.2) \quad H(Sx, Ty) \leq k \max \{d(fx, fy), d(fx, Sx), d(fy, Ty)\}$$

for all $x, y \in X$, where $0 < k < 1$.

If $f(X)$ is d -bounded, and one of $f(X)$ or $S(X)$ or $T(X)$ is an S -complete subspace of X , then f, S and T have a coincidence, i.e., there exists an element $z \in X$ such that

$$fz \in Sz \cap Tz.$$

Proof. Pick $x_0 \in X$. Construct sequences $\{x_n\}$ and $\{y_n\}$ in the following manner. Choose $x_1 \in X$ such that

$$y_1 = fx_1 \in Sx_0.$$

We may choose a point $x_2 \in X$ such that

$$y_2 = fx_2 \in Tx_1$$

and

$$d(y_1, y_2) = d(fx_1, fx_2) \leq \alpha H(Sx_0, Tx_1),$$

where $\alpha = \frac{1}{\sqrt{k}} > 1, 0 < k < 1$. Similarly, we choose a point $x_3 \in X$ such that

$$y_3 = fx_3 \in Sx_2$$

and

$$d(y_2, y_3) \leq \alpha H(Tx_1, Sx_2).$$

Continuing in this fashion, we may choose

$$y_{2n} = fx_{2n} \in Tx_{2n-1}$$

and

$$y_{2n+1} = fx_{2n+1} \in Sx_{2n}$$

such that

$$d(y_{2n}, y_{2n+1}) = d(fx_{2n}, fx_{2n+1}) \leq \alpha H(Tx_{2n-1}, Sx_{2n}).$$

Similarly,

$$d(y_{2n+1}, y_{2n+2}) = d(fx_{2n+1}, fx_{2n+2}) \leq \alpha H(Sx_{2n}, Tx_{2n+1}).$$

By (3.2),

$$\begin{aligned} d(y_{2n}, y_{2n+1}) &= d(fx_{2n}, fx_{2n+1}) \leq \alpha H(Tx_{2n-1}, Sx_{2n}) \\ &\leq \alpha k \cdot \max \{d(fx_{2n-1}, fx_{2n}), d(fx_{2n}, Sx_{2n}), d(fx_{2n-1}, Tx_{2n-1})\} \\ &\leq \alpha k \cdot \max \{d(fx_{2n-1}, fx_{2n}), d(fx_{2n}, fx_{2n+1}), d(fx_{2n-1}, fx_{2n})\}. \end{aligned}$$

This yields

$$d(y_{2n}, y_{2n+1}) \leq \sqrt{k}d(y_{2n-1}, y_{2n}).$$

Similarly,

$$d(y_{2n+1}, y_{2n+2}) \leq \sqrt{k}d(y_{2n}, y_{2n+1}).$$

Both together imply

$$d(y_n, y_{n+1}) \leq \sqrt{k}d(y_{n-1}, y_n), n = 1, 2, 3, \dots$$

So, by Lemma 2.1, the sequence $\{y_n\}$ is a d-Cauchy in $f(X)$. Now suppose the subspace $f(X)$ is S-complete. Then, there exists an element $u \in f(X)$ such that

$$\lim_{n \rightarrow \infty} d(u, y_n) = 0.$$

Notice that the subsequences $\{y_{2n-1}\}$ and $\{y_{2n}\}$ also converge to u . Since $u \in f(X)$, there exists an element $z \in f^{-1}u$ such that $fz = u$. From Lemma 2.2, for each $n \in \{1, 2, 3, \dots\}$, there exists an element $fx_{2n} \in Sz$ such that

$$d(fz_n, fx_{2n}) \leq \varepsilon H(Sz, Tx_{2n-1}),$$

where $\varepsilon = \frac{1}{\sqrt{k}} > 1, 0 < k < 1$.

Let

$$\mu = \lim_{n \rightarrow \infty} d(fz_n, fz).$$

Then by (3.2),

$$\begin{aligned} d(fz_n, fx_{2n}) &\leq \varepsilon k \cdot \max \{d(fz, fx_{2n-1}), d(fz, Sz), d(fx_{2n-1}, Tx_{2n-1})\} \\ &\leq \sqrt{k} \max \{d(fz, fx_{2n-1}), d(fz, fz_n), d(fx_{2n-1}, fx_{2n})\}. \end{aligned}$$

Making $n \rightarrow \infty$, we get

$$\mu \leq \sqrt{k} \max \{0, \mu, 0\}.$$

This gives $\mu = 0$.

Thus, we have

$$\lim_{n \rightarrow \infty} d(fz_n, fz) = 0$$

and

$$\lim_{n \rightarrow \infty} d(fx_{2n}, fz) = 0.$$

So, by (W.4), we get

$$\lim_{n \rightarrow \infty} d(fx_{2n}, fz_n) = 0.$$

Notice that $fx_{2n} \in Tx_{2n-1}$ and $fz_n \in Sz$. So,

$$\lim_{n \rightarrow \infty} d(fx_{2n}, Sz) \leq \lim_{n \rightarrow \infty} d(fx_{2n}, fz).$$

This gives

$$d(fz, Sz) = 0 \text{ and } fz \in Sz.$$

Similar arguments give $fz \in Tz$.

Therefore,

$$fz \in Sz \cap Tz.$$

If $S(X)$ (respectively $T(X)$) is S-complete, then there exists

$$u \in S(X) \subseteq f(X) \text{ (respectively } u \in T(X) \subseteq f(X)),$$

and the above argument establishes the result. ■

Now we apply Theorem 3.1 to obtain the following fixed point theorem.

Theorem 3.2. *Let all the hypotheses of Theorem 3.1 hold. If $ffz = fz$ and f is (IT)-commuting with each of S and T , then the maps f, S and T have a common fixed point.*

Proof. By Theorem 3.1, there exists a $z \in X$ such that $fz \in Sz$ and $fz \in Tz$. As f is (IT)-commuting with each of S and T at z ,

$$fz = f fz \in fSz \subset S fz$$

and

$$fz = f fz \in fTz \subset T fz.$$

Hence

$$fu = u \in Su \cap Tu,$$

where $u = fz$. ■

We remark that the requirement $fz = f fz$ in the above theorem is essential for the existence of a common fixed point. In the absence of this requirement, the maps f , S and T need not have a common fixed point (see, for instance, [19, 22] and [23]).

Corollary 3.3. *Let (X, d) be a d -bounded symmetric space satisfying (W.4). Let $S, T : X \rightarrow CB(X)$ such that*

$$(3.3) \quad H(Sx, Ty) \leq k \max \{d(x, y), d(x, Sx), d(y, Ty)\}$$

for all $x, y \in X$, where $0 < k < 1$. If one of $S(X)$ or $T(X)$ is an S -complete subspace of X then S and T have a common fixed point.

Proof. It comes from Theorem 3.1 when f is the identity map on X . ■

Corollary 3.4. *Let (X, d) be a symmetric space satisfying (W.4). Let $T(X) \subseteq f(X)$ and $f : X \rightarrow X$ and $T : X \rightarrow CB(X)$ such that*

$$(3.4) \quad H(Tx, Ty) \leq k \max \{d(fx, fy), d(fx, Tx), d(fy, Ty)\}$$

for all $x, y \in X$, where $0 < k < 1$.

If $f(X)$ is d -bounded, and one of $f(X)$ or $T(X)$ is an S -complete subspace of X , then f and T have a coincidence, i.e., there exists an element $z \in X$ such that $fz \in Tz$. Further, if fz is a fixed point of f , and f is (IT)-commuting with T , then fz is also a fixed point of T .

Proof. It comes from Theorems 3.1 and 3.2 when $S = T$. ■

Corollary 3.5. *Let (X, d) be a symmetric space satisfying (W.4). Let $f : X \rightarrow X$ and $S, T : X \rightarrow CB(X)$ such that $f(X)$ is d -bounded, and one of $S(X)$ and $T(X)$ is S -complete subspace of X , and $S(X) \cup T(X) \subseteq f(X)$ and satisfying*

$$(3.5) \quad H(Sx, Ty) \leq kd(fx, fy),$$

for all $x, y \in X$, where $0 < k < 1$.

Then f , S and T have a coincidence point z (say). Further, if fz is a fixed point of f , and f is (IT)-commuting with each of S and T , then fz is a common fixed point of f , S and T .

Proof. The proof is obvious as the condition (3.5) is contained in (3.2). ■

We remark that Corollaries 3.4 and 3.5 with $S = T$ are improved versions of Moutawakil [17, Th. 2.2.1] when f is the identity map on X .

Now following Moutawakil [17], we give an application of Corollary 3.4. First following [10, 17, 20] and [27] we give some definitions .

Definition 3.1. A function $F : R \rightarrow [0, 1]$ is a distribution function if

- (v) F is non-decreasing
- (vi) F is left continuous,

(vii)

$$\inf_{x \in R} F(x) = 0$$

and

$$\sup_{x \in R} F(x) = 1.$$

Definition 3.2. Let X be a set and \mathfrak{S} a function defined on $X \times X$ such that $\mathfrak{S}(x, y) = F(x, y)$ is a distribution function. Consider the following conditions:

(viii) $F(x, y, 0) = 0$ for all $x, y \in X$.(ix) $F(x, y) = f$ if and only if $x = y$, where f is the distribution function defined by $f(x) = 0$ if $x \leq 0$, and $f(x) = 1$ if $x > 0$.(x) $F(x, y) = F(y, x)$ for all $x, y \in X$.(xi) If $F(x, y, \alpha) = 1$ and $F(y, z, \beta) = 1$ then $F(x, z, \alpha + \beta) = 1$, for all $x, y, z \in X$.

If \mathfrak{S} satisfies (viii) and (ix), then it is called a PPM-structure on X and the pair (X, \mathfrak{S}) is called a PPM-space and \mathfrak{S} satisfying (x) is said to be symmetric. A symmetric PPM-structure \mathfrak{S} satisfying (xi) is a probabilistic metric structure and the pair (X, \mathfrak{S}) is a probabilistic metric space.

Let (X, \mathfrak{S}) be a symmetric PPM-space. For $\alpha, \gamma > 0$ and $x \in X$, let

$$N_x(\alpha, \gamma) = \{y \in X : F(x, y, \alpha) > 1 - \gamma\}.$$

A T_1 topology $t(\mathfrak{S})$ on X is defined as follows:

$$t(\mathfrak{S}) = \{U \subseteq X : \text{for each } x \text{ in } U, \\ \text{there exists } \alpha > 0, \text{ such that } N_x(\alpha, \alpha) \subseteq U\}.$$

Definition 3.3. Let (X, \mathfrak{S}) be a symmetric PPM-space. A sequence $\{x_n\}$ in X is called a fundamental sequence if

$$\lim_{n, m \rightarrow \infty} F(x_n, x_m, t) = 1$$

for all $t > 0$. The space is called F-complete if for every fundamental sequence $\{x_n\}$ in X , there exists an $x \in X$ such that

$$\lim_{n \rightarrow \infty} F(x_n, x, t) = 1$$

for all $t > 0$.

In space (X, \mathfrak{S}) , the condition **(W.4)** is equivalent to the following:

(C.4)

$$\lim_{n \rightarrow \infty} F(x_n, x, t) = 1$$

and

$$\lim_{n \rightarrow \infty} F(x_n, y_n, t) = 1$$

imply

$$\lim_{n \rightarrow \infty} F(y_n, x, t) = 1$$

for all $t > 0$.

Definition 3.4. Let (X, \mathfrak{S}) be a symmetric PPM-space. A nonempty subset P of X is called \mathfrak{S} -closed if and only if $\overline{P}_{\mathfrak{S}} = P$, where

$$\overline{P}_{\mathfrak{S}} = \left\{ x \in X : \sup_{a \in P} F(x, a, t) = 1 \text{ for all } t > 0 \right\}.$$

For the details of the topological preliminaries, one may refer to [6] and [20]. In all that follows we denote the set of all nonempty \mathfrak{S} -closed subsets of X by $CB_{\mathfrak{S}}(X)$ and the set of nonnegative real numbers by R^+ .

The following is a slightly modified version of Moutawakil [17, Prop. 2.3.1].

Proposition 3.6. ([17]). *Let (X, \mathfrak{S}) be a symmetric PPM-space. Let p a compatible symmetric function for $t(\mathfrak{S})$. For $A, B \in CB(X)$, set*

$$E(A, B, \varepsilon) = \min \left\{ \inf_{a \in A} \sup_{b \in B} F(a, b, \varepsilon); \inf_{b \in B} \sup_{a \in A} F(a, b, \varepsilon) \right\}, \varepsilon > 0,$$

and

$$P(A, B) = \max \left\{ \sup_{a \in A} \inf_{b \in B} p(a, b); \sup_{b \in B} \inf_{a \in A} p(a, b) \right\}.$$

Let $f : X \rightarrow X$ and $T : X \rightarrow CB(X)$. Then, if

$$F(fx, fy, t) > 1 - t$$

implies

$$E(Tx, Ty, kt) > 1 - kt, 0 \leq k < 1,$$

for all $t > 0$ and all $x, y \in X$, implies that

$$P(Tx, Ty) \leq kp(fx, fy).$$

In a symmetric PPM space (X, \mathfrak{S}) , if p is a compatible symmetric function on $t(\mathfrak{S})$ then

$$CB_{\mathfrak{S}}(X) = CB(X),$$

where $CB(X)$ is the set of all nonempty p -closed subsets of (X, p) .

Hicks and Rhoades [10] obtained the following result showing that each symmetric PPM-space admits a compatible symmetric function.

Theorem 3.7. ([10]). *Let (X, \mathfrak{S}) be a symmetric PPM-space. Let $p : X \times X \rightarrow R^+$ be a function defined as follows:*

$$p(x, y) = \begin{cases} 0 & \text{if } y \in N_x(t, t) \text{ for all } t > 0, \\ \sup \{t : y \notin N_x(t, t), 0 < t < 1\} & \text{otherwise.} \end{cases}$$

Then

- (i) $p(x, y) < t$ if and only if $F(x, y, t) > 1 - t$;
- (ii) p is a compatible symmetric for $t(\mathfrak{S})$;
- (iii) (X, \mathfrak{S}) is F -complete if and only if (X, p) is F -complete.

Now we present the following result in a symmetric PPM-space.

Theorem 3.8. *Let (X, \mathfrak{S}) be a F -complete symmetric PPM-space that satisfies (C.4) such that p is a compatible symmetric function for $t(\mathfrak{S})$. Let $f : X \rightarrow X$ and $T : X \rightarrow CB_{\mathfrak{S}}(X)$ be maps such that*

$$F(fx, fy, t) > 1 - t$$

implies

$$E(Tx, Ty, kt) > 1 - kt, 0 \leq k < 1,$$

for all $x, y \in X$.

Then there exists a $z \in X$ such that $fz \in Tz$. Further, if f and T are (IT)-commuting just at z , and if fz is a fixed point of f , then f and T have a common fixed point.

Proof. Clearly (X, p) is a bounded and S-complete symmetric space and we have

$$p(fx, fy) < t$$

if and only if

$$F(fx, fy, t) > 1 - t.$$

Given $\varepsilon > 0$, put $t = p(fx, fy) + \varepsilon$.

Then,

$$F(fx, fy, t) > 1 - t.$$

Therefore

$$F(Tx, Ty, kt) > 1 - kt, 0 \leq k < 1,$$

for all $x, y \in X$.

From Proposition 3.6, we obtain

$$P(Tx, Ty) \leq kt = kp(fx, fy) + k\varepsilon.$$

As $\varepsilon > 0$ is arbitrary, on letting $\varepsilon \rightarrow 0$,

$$P(Tx, Ty) \leq kp(fx, fy).$$

An application of Corollary 3.5 with $S = T$ completes the proof. ■

Corollary 3.9. ([17]) *Let (X, \mathfrak{S}) be a F-complete symmetric PPM-space that satisfies (C.4) such that p is a compatible symmetric function for $t(\mathfrak{S})$. Let $T : X \rightarrow CB_{\mathfrak{S}}(X)$ be a multivalued mapping such that*

$$F(x, y, t) > 1 - t$$

implies

$$E(Tx, Ty, kt) > 1 - kt, 0 \leq k < 1,$$

for all $x, y \in X$ and $t > 0$. Then there exists $z \in X$ such that $z \in Tz$.

Proof. It comes from Theorem 3.8 when f is the identity map on X . ■

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